

Rotations and reflections of geometric objects in the plane - with an emphasis on animating the transformation.

```
> restart: with(plots): with(plottools):with(LinearAlgebra):
Warning, the name changecoords has been redefined
Warning, the assigned name arrow now has a global binding
> p := [<1,1>, <-1,1>, <-1,-1>, <1,-1>];
# p := [<2,0>, <3,2>, <1,4>, <0,2>, <-1,3>, <-2,0>, <-2,-2>, <0,-2>];
```

$$p := \left[ \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -1 \end{bmatrix} \right]$$

(1)

Construct a regular n-gon on the unit circle.

```
> nGon := n -> [seq(<cos((4*i+2-n)*Pi/(2*n)), sin((4*i+2-n)*Pi/(2*n))
>, i=0..(n-1))];
p := nGon(6);
```

$$nGon := n \rightarrow \left[ \text{seq} \left( \left\langle \cos \left( \frac{1}{2} \frac{(4i+2-n)\pi}{n} \right), \sin \left( \frac{1}{2} \frac{(4i+2-n)\pi}{n} \right) \right\rangle, i=0..n-1 \right) \right]$$

$$p := \left[ \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix} \right]$$

(2)

```
> for i from 1 to (nops(p)-1) do
  l[i] := [p[i], p[i+1]];
end do;
l[nops(p)] := [p[nops(p)], p[1]];
nops(1);
```

$$l_1 := \left[ \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right]$$

$$l_2 := \left[ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix} \right]$$

$$l_3 := \left[ \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix} \right]$$

$$l_4 := \left[ \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \end{bmatrix} \right]$$

$$l_5 := \left[ \begin{array}{c} \left[ \begin{array}{c} -1 \\ 0 \end{array} \right], \left[ \begin{array}{c} -\frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{array} \right] \end{array} \right]$$

$$l_6 := \left[ \begin{array}{c} \left[ \begin{array}{c} -\frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{array} \right], \left[ \begin{array}{c} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{array} \right] \end{array} \right]$$

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(3)

The colors list will allow objects with up to 16 defining points.

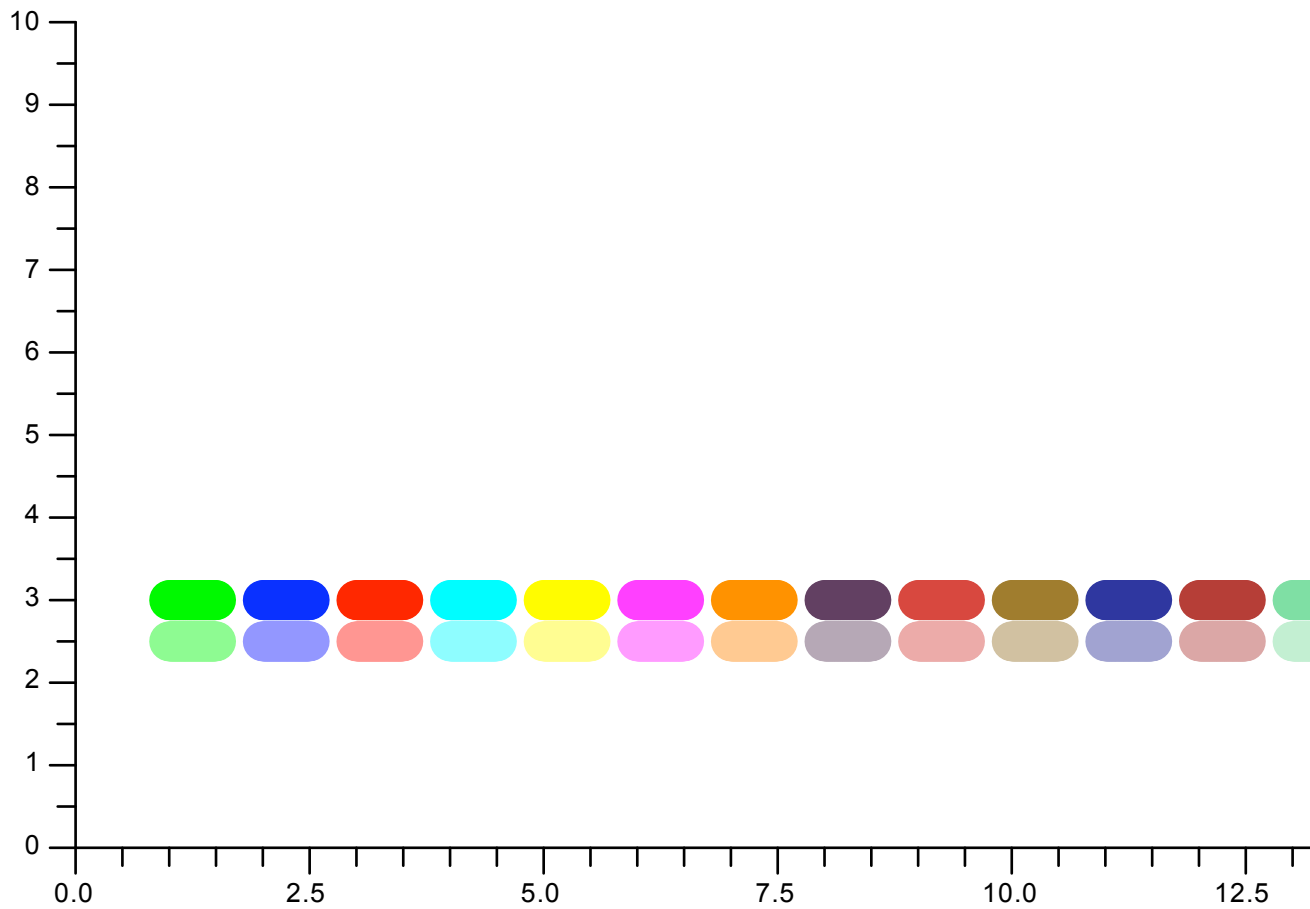
```
> colors := [green, blue, red, cyan, yellow, magenta, coral, violet, orange,
             sienna, navy, brown, aquamarine, gold, maroon, khaki]:
```

Create lighter shades of each color.

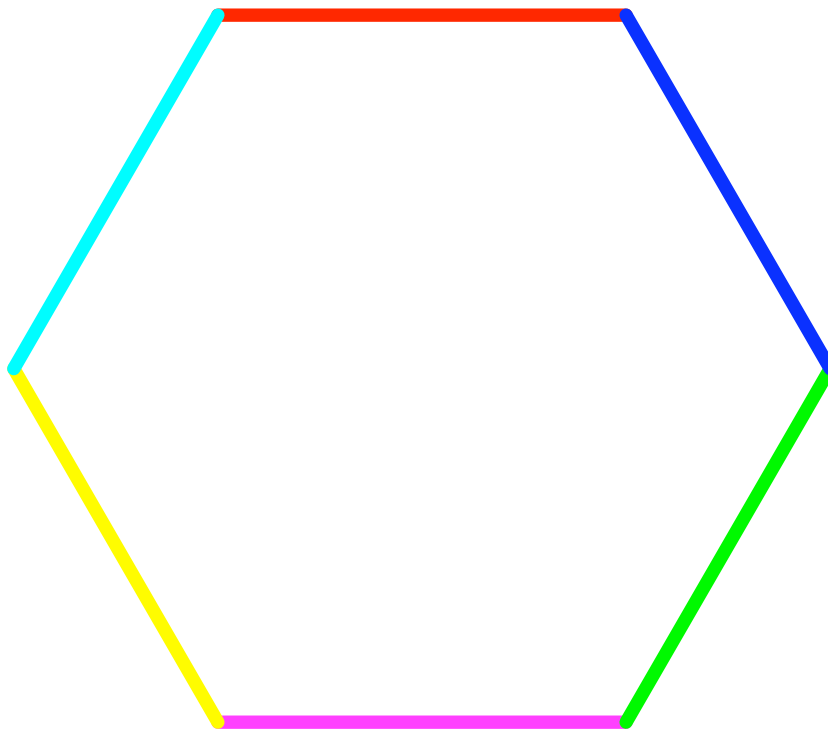
```
> lcolors := [COLOR(RGB, .5, 1, .5), COLOR(RGB, .5, .5, 1), COLOR(RGB, 1, .5,
.5), COLOR(RGB, .5, 1, 1), COLOR(RGB, 1, 1, .5), COLOR(RGB, 1, .5, 1), COLOR
(RGB, 1, 0.7490196100, .5), COLOR(RGB, 0.6549019600, 0.5921568650,
0.6549019600), COLOR(RGB, .9, 0.5980392150, 0.5980392150), COLOR(RGB,
0.7784313750, 0.7098039200, 0.5686274500), COLOR(RGB, 0.5686274500,
0.5686274500, 0.7784313750), COLOR(RGB, 0.8235294100, 0.5823529400,
0.5823529400), COLOR(RGB, 0.7196078450, 0.9294117650, 0.7882352950),
COLOR(RGB, .9, 0.7490196100, 0.5980392150), COLOR(RGB, 0.7784313750,
0.5686274500, 0.7098039200), COLOR(RGB, 0.8117647050, 0.8117647050,
0.6862745100)]:
```

Show the colors with the lighter shades in the order they are used in plots.

```
> for i from 1 to 16 do
    tp[i] := plot([t, 3, t=i..i+.5], 0..17, 0..10, color=colors[i],
thickness=15):
    tpl[i] := plot([t, 2.5, t=i..i+.5], 0..17, 0..10, color=lcolors[i],
thickness=15):
end do:
display([seq(tp[i], i=1..16), seq(tpl[i], i=1..16)]);
```



```
> for i from 1 to nops(p) do
  lp[i] := pointplot(l[i],color = colors[i], thickness = 5,
connect=true):
end do:
> display([seq(lp[i],i=1..nops(p))],scaling=constrained,axes=None);
```



```
> rotmat := alpha -> <<cos(alpha), sin(alpha)> | <-sin(alpha), cos(alpha)>>;
```

$$rotmat := \alpha \rightarrow \langle \langle \cos(\alpha), \sin(\alpha) \rangle \mid \langle -\sin(\alpha), \cos(\alpha) \rangle \rangle \quad (4)$$

```
> rot90 := rotmat(Pi/2);
```

$$rot90 := \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \quad (5)$$

```
> multmatbylist := (multmat, listofvecs) ->
  map((x,y) -> y.x, listofvecs, multmat):
```

```
> rotateObj := (listoflistofvecs, ang) -> seq(multmatbylist(rotmat(ang), listoflistofvecs[i]), i=1..nops(p));
```

```
rotateObj := (listoflistofvecs,
  ang) -> seq(multmatbylist(rotmat(ang), listoflistofvecs_i), i=1..nops(p)) \quad (6)
```

```
> ObjRot1 := rotateObj(1, Pi/3);
l[1];
ObjRot1[1];
type([ObjRot1], list);
[ObjRot1][1];
l[1];
```

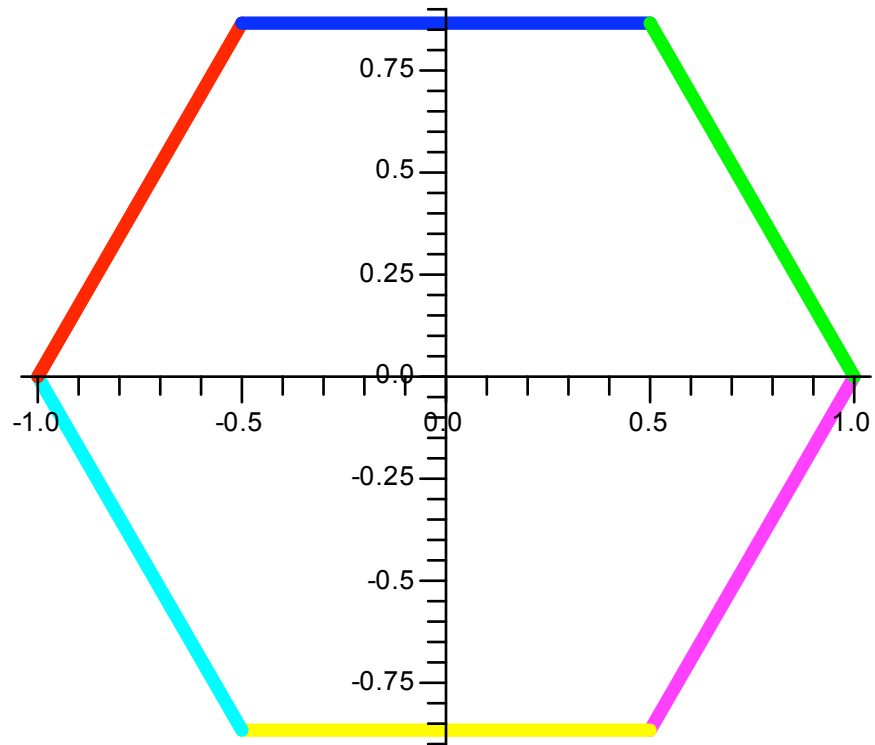
$$\begin{aligned}
ObjRot1 := & \left[ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} \frac{-1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} \frac{-1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \right. \\
& \left. \begin{bmatrix} \frac{-1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} \frac{-1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right] \\
& \left[ \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right] \\
& \left[ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix} \right] \\
& \text{true} \\
& \left[ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix} \right] \\
& \left[ \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix} \right]
\end{aligned}$$

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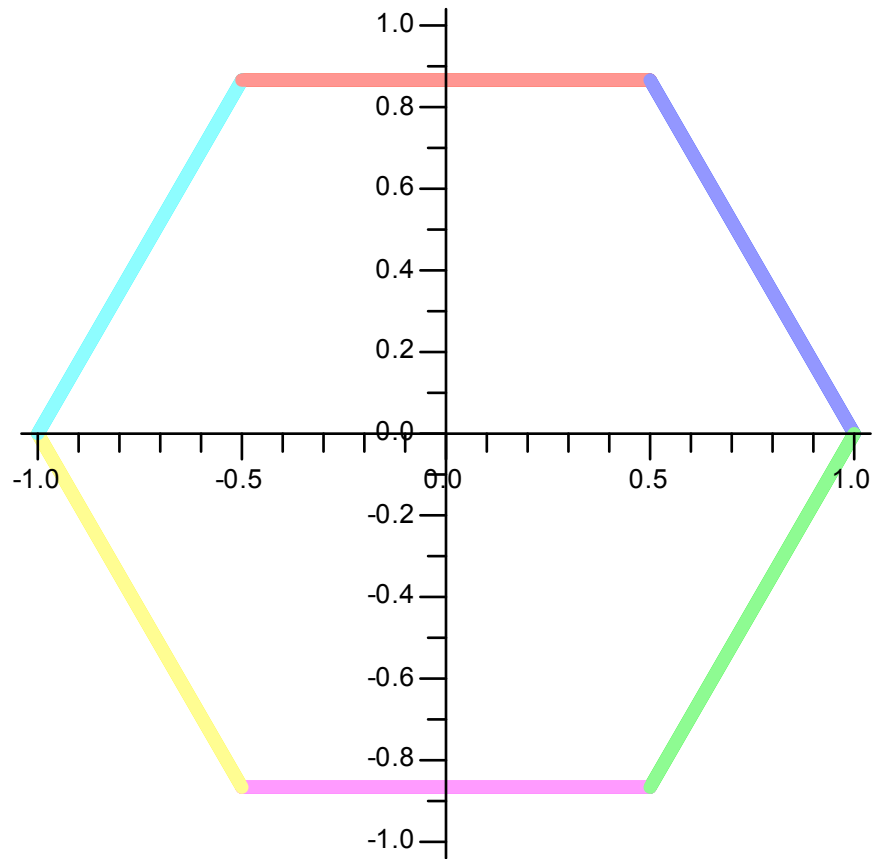
```

> for i from 1 to nops(p) do
  ObjRotp[i] := pointplot(ObjRot1[i],color = colors[i], thickness
= 5,connect=true):
end do:
display([seq(ObjRotp[i],i=1..nops(p))],scaling=constrained);

```



```
> display([seq(display([seq(pointplot(l[i],color = lcolors[i],
thickness = 5,connect=true),i=1..nops(p)),seq(pointplot
(multmatbylist(rotmat((counta/18)*Pi/2),l[i]),color=colors[i],
connect=true,thickness=5),i=1..nops(p))]), counta=0..18)],
insequence = true);
```



```
> print(1);
nops(1); 1[1];1[2];
```

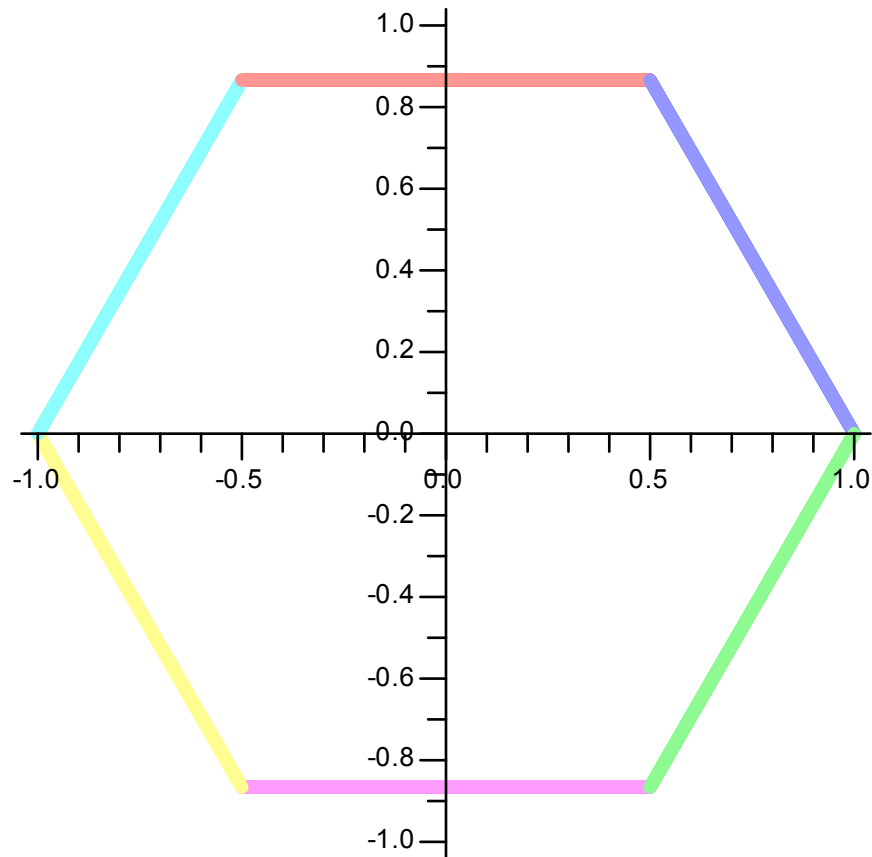
$$\text{table} \left( \left[ \left[ \begin{matrix} 1 \\ \left[ \begin{matrix} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{matrix} \end{matrix} \right], \left[ \begin{matrix} 1 \\ 0 \end{matrix} \right] \right], 2 = \left[ \begin{matrix} 1 \\ 0 \end{matrix} \right], \left[ \begin{matrix} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{matrix} \right] \right], 3 = \left[ \begin{matrix} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{matrix} \right], \left[ \begin{matrix} -\frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{matrix} \right] \right], \\
 5 = \left[ \begin{matrix} -1 \\ 0 \end{matrix} \right], \left[ \begin{matrix} -\frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{matrix} \right] \right], 4 = \left[ \begin{matrix} -\frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{matrix} \right], \left[ \begin{matrix} -1 \\ 0 \end{matrix} \right] \right], \\
 6 = \left( \left[ \begin{matrix} -\frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{matrix} \right], \left[ \begin{matrix} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{matrix} \right] \right)$$

$$\left[ \begin{array}{c} \left[ \begin{array}{c} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{array} \right], \left[ \begin{array}{c} 1 \\ 0 \end{array} \right] \\ \left[ \begin{array}{c} 1 \\ 0 \end{array} \right], \left[ \begin{array}{c} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{array} \right] \end{array} \right] \quad (8)$$

```
> AnimRotate := proc(l,ang)
  local NumSteps;
  NumSteps := ceil(36*abs(ang)/Pi);
  display([seq(display([seq(pointplot(l[i],color = lcolors[i],
  thickness = 5,connect=true),i=1..nops(p)),seq(pointplot
  (multmatbylist(rotmat((counta/NumSteps)*ang),l[i]),color=colors[i]
  ,connect=true,thickness=5),i=1..nops(p)))]), counta=0..NumSteps)],
  scaling=constrained, insequence = true)
end proc;
```

```
AnimRotate := proc(l, ang)
  local NumSteps;
  NumSteps := ceil((36 * abs(ang))/Pi);
  display([seq(display([seq(pointplot(
  l[i], color = lcolors[i], thickness = 5, connect = true),
  i = 1 .. nops(p)), seq(pointplot(multmatbylist(rotmat((counta * ang)/NumSteps),
  l[i]), color = colors[i], connect = true, thickness = 5), i = 1 .. nops(p)))]),
  counta = 0 .. NumSteps)], scaling = constrained, insequence = true)
end proc
```

```
> AnimRotate(l,Pi/3);
```



Now work on the reflections. Basic reflection matrix reflects in steps across x-axis, but we represent this as rotation around the x-axis in R3.

```
> refinxmat := alpha -> <<1, 0, 0>|<0, cos(alpha), sin(alpha)>|<0, -sin(alpha), cos(alpha)>>;
refinxmat := alpha -> <<1, 0, 0>|<0, cos(alpha), sin(alpha)>|<0, -sin(alpha), cos(alpha)>> (10)
```

```
> refinxmat(Pi);
[ 1  0  0 ]
[ 0 -1  0 ]
[ 0  0 -1 ] (11)
```

To reflect in the line at angle theta we need to conjugate by the change of basis matrix

```
> chbasis := theta -> <<cos(theta), sin(theta), 0>|<-sin(theta), cos(theta), 0>|<0, 0, 1>>;
refmat := (theta, alpha) -> chbasis(theta).refinxmat(alpha).
(chbasis(theta))^-1;
chbasis := theta -> <<cos(theta), sin(theta), 0>|<-sin(theta), cos(theta), 0>|<0, 0, 1>>
refmat := (theta, alpha) -> chbasis(theta).refinxmat(alpha). (1 / chbasis(theta)) (12)
```

```
> refmat(3*Pi/4,Pi);
```

$$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix}$$

(13)

To reflect a vector we embed into R3, apply the reflection matrix, and then project back to R2.

```
> projembmultmatbylist :=(multmat, listofvecs)->
  map((x,y)-> <(y.<x[1],x[2],0>)[1],(y.<x[1],x[2],0>)[2]>,
  listofvecs,multmat):
```

```
> projembmultmatbylist(refmat(Pi/4,Pi),l[1]);
```

$$\begin{bmatrix} -\frac{1}{2}\sqrt{3} \\ \frac{1}{2} \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

(14)

```
> reflectObj := (listoflistofvecs,ang) -> seq(projembmultmatbylist
  (refmat(ang,Pi),listoflistofvecs[i]),i=1..nops(p));
```

```
reflectObj := (listoflistofvecs,
```

```
  ang) -> seq(projembmultmatbylist(refmat(ang, pi), listoflistofvecs_i), i = 1 .. nops(p))
```

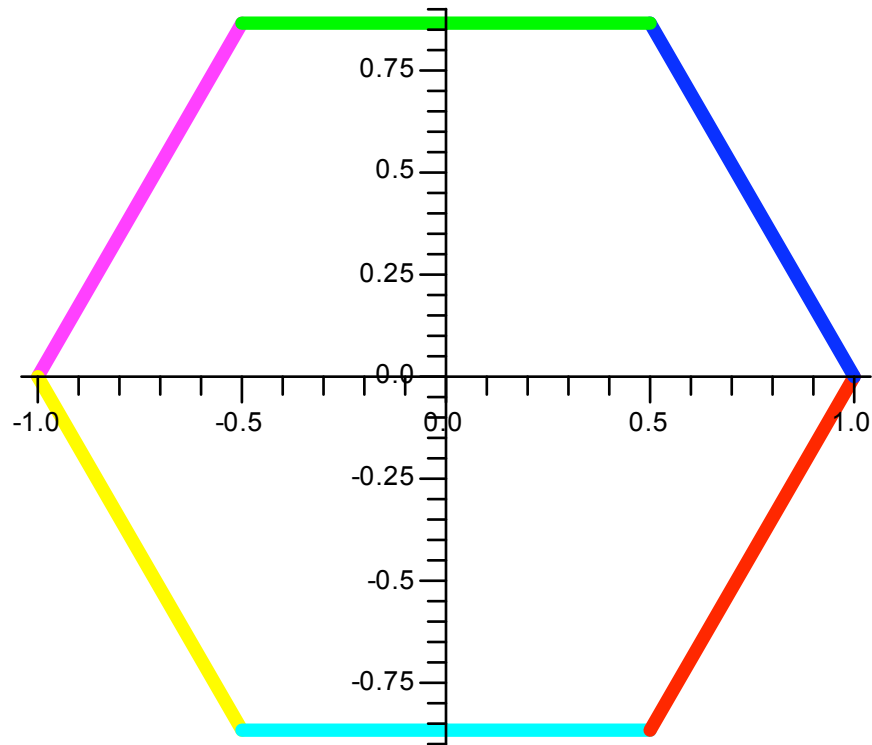
(15)

```
> refObj1 := reflectObj(1,Pi/6);
```

$$\text{refObj1} := \left[ \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{bmatrix} \right]$$

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```
> for i from 1 to nops(p) do
  refObj1p[i] := pointplot(refObj1[i],color = colors[i],
  thickness = 5,connect=true):
end do:
display([seq(refObj1p[i],i=1..nops(p))],scaling=constrained);
```



```

>
> AnimReflect := proc(l,ang)
display([seq(display([plot([cos(ang)*t,sin(ang)*t,t=-1.1..1.1],
linestyle=DOT,thickness=2,color=black),seq(pointplot(l[i],color =
lcolors[i], thickness = 5,connect=true),i=1..nops(p)),seq
(pointplot(projembmultmatbylist(refmat(ang,(counta/18)*Pi),l[i]),
color=colors[i],connect=true,thickness=5),i=1..nops(p)))]), counta=
0..18)], insequence = true,scaling=constrained)
end proc;

```

*AnimReflect* := **proc**(*l*, *ang*) (17)

```

display([seq(display([plot([cos(ang)*t,sin(ang)*t,
t = -1.1 ..1.1], linestyle=DOT, thickness=2, color=black),seq(pointplot(
l[i], color=lcolors[i], thickness=5, connect=true),
i=1..nops(p)),seq(pointplot(projembmultmatbylist(refmat(ang,1/18*counta*Pi),
l[i], color=colors[i], connect=true, thickness=5),i=1..nops(p)))]), counta=0..18)],
insequence=true,scaling=constrained)

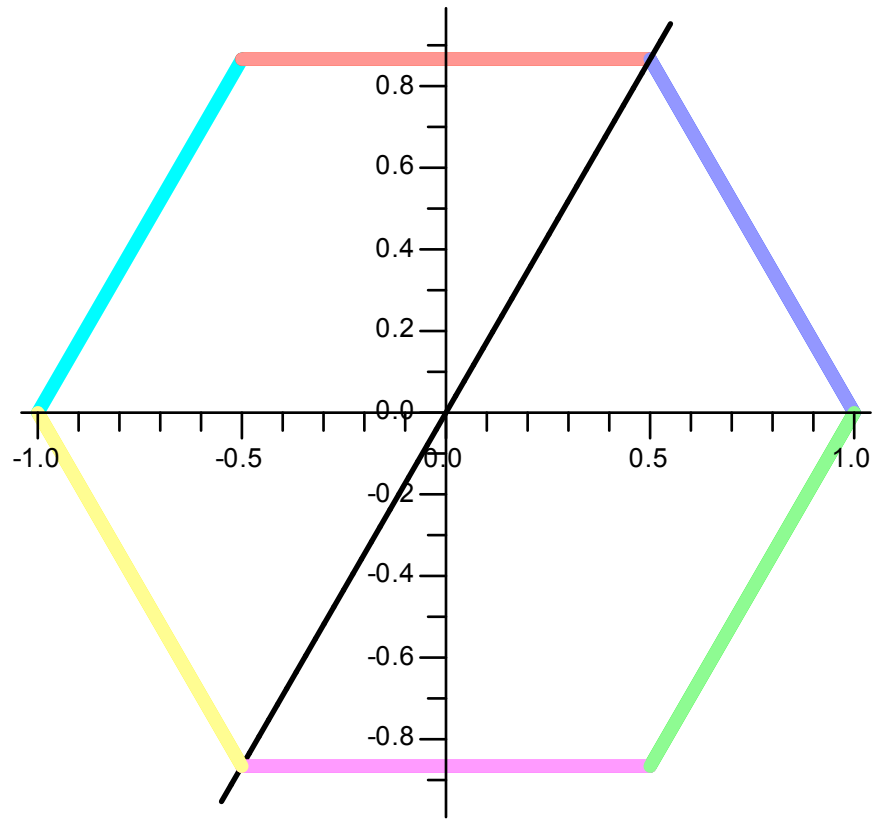
```

**end proc**

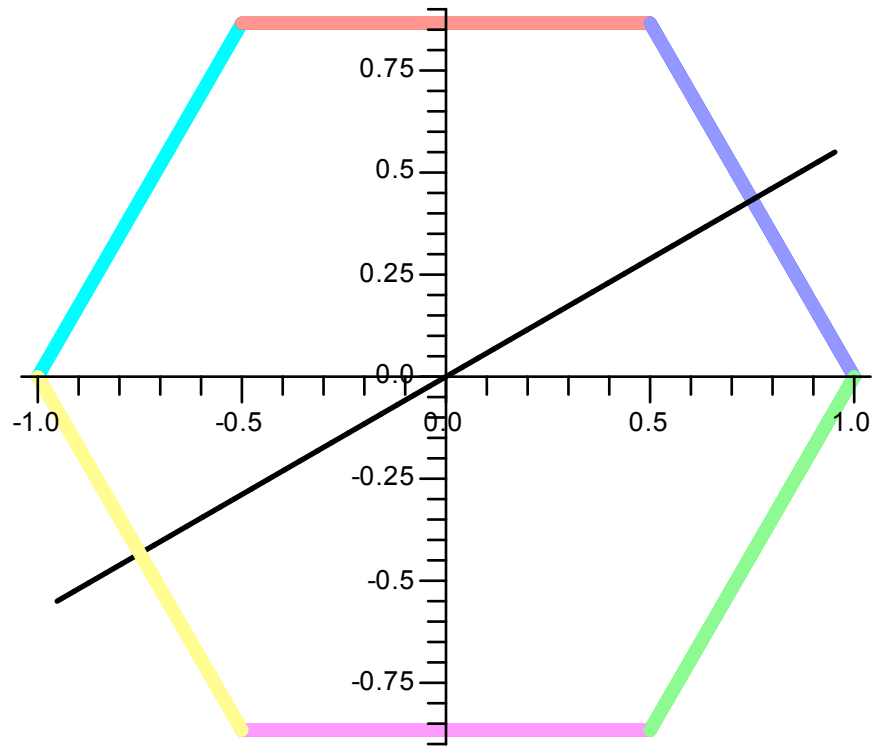
```

> AnimReflect(1,Pi/3);

```



```
> AnimReflect(1, Pi/6);
```



> **l;**

*l*

(18)

> *ObjRotl;*

$$\begin{aligned}
 & \left[ \begin{matrix} 1 \\ 0 \end{matrix} \right], \left[ \begin{matrix} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{matrix} \right], \left[ \begin{matrix} \frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{matrix} \right], \left[ \begin{matrix} -\frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{matrix} \right], \left[ \begin{matrix} -\frac{1}{2} \\ \frac{1}{2}\sqrt{3} \end{matrix} \right], \left[ \begin{matrix} -1 \\ 0 \end{matrix} \right] \\
 & , \left[ \begin{matrix} -1 \\ 0 \end{matrix} \right], \left[ \begin{matrix} -\frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{matrix} \right], \left[ \begin{matrix} -\frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{matrix} \right], \left[ \begin{matrix} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{matrix} \right], \left[ \begin{matrix} \frac{1}{2} \\ -\frac{1}{2}\sqrt{3} \end{matrix} \right], \left[ \begin{matrix} 1 \\ 0 \end{matrix} \right]
 \end{aligned}$$

(19)

>